

Contents

Title	i
Declaration	v
Certificate of Approval	vii
Certificate	ix
Acknowledgements	xi
List of Abbreviations	xii
List of Important Symbols	xv
List of Figures	xix
Abstract	xxiii
1 Introduction	1
1.1 Introduction	2
1.2 State-of-the-Art LRT Detectors in Compound-Gaussian Clutter . .	2
1.3 Motivation	4
1.4 Objectives of the Thesis Work	5
1.5 Contributions Made in the Thesis	6
1.6 Outline of the Thesis	7

2 Background	11
2.1 Introduction	12
2.2 Target Detection in Scanning Radar	12
2.2.1 A Conventional MTI Radar Detector	14
2.2.2 Signal Processing in MTI Filter	14
2.3 LRT Based Detection	16
2.3.1 Detection Using LLRT	16
2.3.2 Detection Using GLRT	17
2.3.3 LRT Detection in Non-Gaussian Clutter	19
2.4 CFAR Methods for Target Detection	20
2.4.1 Conventional CFAR Detection Schemes	20
2.4.2 CFAR LRT Detection in Non-Gaussian Clutter	22
2.5 The Non-Gaussian Clutter Models	23
2.6 Measured Data of Non-Gaussian Clutter	26
2.6.1 Real Clutter From Land Illuminated Area	27
2.6.2 Real Clutter From an Illuminated Area of Sea Surface	30
3 A Comparative Performance of LRT Detectors Available in the Literature	31
3.1 Introduction	32
3.1.1 Organization of the Chapter	34
3.2 Model of the Signals	34
3.2.1 Model of the Target Signal	34
3.2.2 The Compound-Gaussian Model of K-distributed Clutter	35
3.2.3 The AWGN	36
3.3 The LRT Detection in the Presence of Compound-Gaussian Clutter and AWGN	36
3.3.1 The LLRT Detection Scheme	37
3.3.2 The GLRT Detection Scheme	41
3.3.3 Experimental Studies on the Performance of LLRT and GLRT Detectors	43
3.4 The MF Detector in Clutter with Partially Correlated Texture	47
3.4.1 Performance Analysis	48
3.4.2 Experimental Studies	50
3.5 Conclusions	53

CONTENTS

4 An Accurate K-Distributed Model for the Clutter	55
4.1 Introduction	56
4.1.1 Organization of the Chapter	58
4.2 The K-distributed Clutter in Scanning Radar Application	58
4.2.1 The Macroscopic Phenomena of Clutter Generation	59
4.2.2 Analysis of the Measured Clutter Data	60
4.3 The Proposed K-distributed Clutter Model	64
4.4 Validation of the Proposed Clutter Model Using Measured Clutter Data	69
4.4.1 Parameter Estimation for the Proposed Clutter Model	69
4.4.2 Simulation of the Clutter from Proposed Model	72
4.4.3 Comparison of the ACF and <i>pdf</i> of Simulated and Measured Clutter Data	75
4.5 Conclusions	80
5 Proposed Scheme for Target Detection in the Accurately Modelled K-Distributed Clutter	83
5.1 Introduction	84
5.1.1 Organization of the Chapter	86
5.2 System Model	86
5.2.1 The Binary Hypothesis	86
5.2.2 The GLRT Statistic	87
5.2.3 Structure of the Clutter Covariance Matrix, \mathbf{M}_c	88
5.3 The Proposed GLRT Detection Scheme	89
5.4 The Proposed Technique for Estimating the Varying Texture	94
5.5 Performance Analysis of the Proposed GLRT Detector	97
5.6 Numerical and Simulation Results	101
5.7 Conclusions	106
6 CFAR GLRT Detection Using Proposed Estimation Techniques	109
6.1 Introduction	110
6.1.1 Organization of the Chapter	112
6.2 The GLRT Based CFAR Detector	112
6.2.1 The MF Detector with an Adaptive Threshold	113
6.2.2 CFAR Detection in Compound-Gaussian Clutter	114

CONTENTS

6.2.3	The Conventional Moving Window (MW) Estimator for Varying Texture	115
6.3	On-line Estimation of Clutter Covariance Matrix	116
6.3.1	The Proposed Technique for Varying Texture Estimation	117
6.3.2	Application of the Proposed Estimator to Real Clutter Data	120
6.3.3	Estimation of the Clutter Covariance Matrix, \mathbf{M}_c	121
6.4	The Proposed Technique for Estimating \mathbf{M}_c Using Clutter Data of Several Scans	124
6.4.1	Estimation of Varying Texture Using the Estimates of the Previous Scan	124
6.4.2	The Complete Structure of the Texture Estimator, \mathbf{B}	128
6.5	The Proposed CFAR GLRT Detector	130
6.5.1	The Complete GLRT Detection Scheme Using the Estimator ‘ \mathbf{B} ’	130
6.5.2	Sensitivity of Detection Threshold to Texture Fluctuation	131
6.5.3	Experimental Studies on the CFAR Behavior and Detection Performance	133
6.6	Conclusions	136
7	Conclusions	139
7.1	Concluding Remarks	140
7.1.1	Performances of LRT Detectors Available in the Literature	141
7.1.2	Accurate K-distributed Clutter Model	142
7.1.3	GLRT Detection in Clutter with Varying Texture	144
7.1.4	CFAR GLRT Detection Using Proposed Estimators	145
7.2	Scope for Future Work	146
References		148
Publications from the Thesis Work		159
Curriculum Vitae		161