Curriculum Vitae

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List of Publications from this Work:

Book Chapter :

i) Roy S.S., Sen Choudhury P., Pratihar D.K., "Dynamic modeling of energy efficient hexapod robot's locomotion over gradient terrains", *Trends in Intelligent Robotics, Communications in Computer and Information Science* 103, P. Vadakkepat et al. (Eds.), **Springer-Verlag** Berlin Heidelberg, 2010, pp. 138-145, (ISBN-13: 978-3-642-15809-4).

International Journal:

1. Roy S. S., Singh A.K., Pratihar D.K., "Estimation of optimal feet forces and joint torques for on-line control of six-legged robot", ***Robotics and Computer Integrated Manufacturing***, 27(5), 2011, pp. 910-917.
2. Roy S. S., Pratihar D.K., "Soft computing-based approaches to predict energy consumption and stability margin of six-legged robots moving on gradient terrains", ***Applied Intelligence***. <in-press>

3. Roy S. S., Pratihar D.K., "Dynamic modeling and energy efficiency analysis of six-legged robot walking on flat and sloping surfaces", ***Mathematics and Computers in Simulation***. <under review>
4. Roy S. S., Pratihar D.K., "Kinematics and dynamic analyses of wave-turning gaits of a six-legged robot", ***Mechanism and Machine Theory***. <under review>
5. Roy S. S., Pratihar D.K., "Effects of turning gait parameters on energy consumption and stability of a six-legged walking robot", ***Robotics and Autonomous Systems***. <under review>
6. Roy S. S., Pratihar D.K., "Soft computing-based expert systems to predict energy consumption and stability margin in turning gaits of six-legged robots", ***Expert Systems with Applications***. <under review>

Conference:

i. Roy S.S., Singh A.K., Pratihar D.K., "analysis of six-legged walking robots", *Proc. of* ***14th National Conference on Machine and Mechanisms*** (NaCoMM-2009), NIT, Durgapur, 2009, pp. 259-265.

ii. Roy S.S., Pratihar D.K., "Dynamic modeling of crab walking of a hexapod robot", *Proc. of* ***5th International Conference on Theoretical, Applied, Computational and Experimental Mechanics*** (ICTACEM-2010), IIT, Kharagpur, 2010, pp. 276-278.

iii. Roy S.S., Pratihar D.K., "Dynamic modeling of energy efficient crab walking of hexapod robot", *Proc. of* ***2nd International Conference on Mechanical, Industrial, and Manufacturing Technologies*** (MIMT 2011), Singapore, 2011, pp. 178-183.

iv. Roy S.S., Pratihar D.K., "Dynamic modeling and energy consumption analysis of crab walking of a six-legged robot", *Proc. of* ***IEEE International Conference on Technologies for Practical Robot Applications***, Massachusetts, USA, 2011, pp. 82-87.

v. Roy S.S., Pratihar D.K., "Dynamic modeling, stability and energy consumption analysis of turning motion of realistic hexapod walking robots", *Proc. of the* ***ASME 2011 International Design Engineering Technical Conference and Computers and Information in Engineering Conference***, Washington, DC, USA, 2011.

vi. Roy S.S., Pratihar D.K., "Study on energy consumption in turning motion of hexapod walking robots", *Proc. of the* ***International Conference on Mechanical Engineering, 2011 World Congress on Engineering,*** London, UK, 2011, pp. 2349-2354.

vii. Roy S.S., Pratihar D.K., "Adaptive neuro-fuzzy expert systems for predicting energy consumption and stability margin in crab walking of six-legged robots", *Proc. of the* ***IEEE Recent Advances in Intelligent Computational Systems***, Trivandrum, India, 2011. <accepted>