

2.3.1.2	The ramification problem	28
2.3.1.3	The qualification problem	29
2.3.2	The Chronos	29
2.3.3	The Time Specialist	30
2.3.4	McDermott's temporal logic	30
2.3.5	Allen's interval algebra	32
2.3.6	Event Calculus (EC)	34
2.3.7	Time Map Manager (TMM)	35
2.3.8	Shoham's temporal logic	37
2.3.9	Other approaches	38
2.4	Complexity issues	39
2.5	Conclusion	40
3	Reason maintenance system in planning	43
3.1	Introduction	43
3.2	Nonmonotonicity in planning	44
3.3	RMS as a tool for nonmonotonic reasoning	46
3.4	Issues in current planning research	47
3.5	Reason maintenance	49
3.5.1	Use of reason maintenance	49
3.5.2	RMS architecture	50
3.5.3	Justification based TMS (RMS)	51
3.5.3.1	Definition and terminology	52
3.5.3.2	Dependency Directed Backtracking (DDB)	54
3.5.3.3	Related work	55
3.5.4	Assumption based TMS	55
3.6	RMS application to planning	56
3.6.1	Use of reason maintenance in planning	57

3.6.2	RMS applications to reasoning with actions	59
3.6.2.1	The earliest systems	59
3.6.2.2	Action representation in KEEworlds	60
3.6.2.3	Plan network maintenance system (PNMS)	60
3.6.2.4	Other research	61
3.7	Current status	61
3.8	Plan logic representation	63
3.9	Conclusion	64
4	Event scheduling using Allen's interval logic	65
4.1	Introduction	65
4.2	Allen's interval algebra	66
4.3	Event scheduling using Allen's algebra	72
4.4	Allen and Koomen's planner	75
4.4.1	Description of action	79
4.4.1.1	Action Paint	79
4.4.1.2	Unstack	79
4.4.2	The new strategy	81
4.5	Conclusion	83
5	Representing action and time in an RMS based framework	85
5.1	Introduction	85
5.2	Representation of plan as a D-net	86
5.2.1	The modified D-net	86
5.2.2	Temporal network (T-net)	88
5.2.3	Representing action as dependencies	88
5.2.4	Representation of time	90
5.3	Resources in D-net	93

5.4	Functions on D-net and T-net	93
5.4.1	D-net functions	93
5.4.2	T-net functions	95
5.5	Representing action at various levels of abstraction	95
5.6	Temporal abstraction	96
5.6.1	Durational relations	96
5.6.1.1	Mapping of durational and relational constraints	97
5.7	Reasoning with plan network	98
5.7.1	Algorithm for truth propagation	99
5.7.1.1	Analysis of the propagate-truth algorithm	101
5.8	Design and architecture	104
5.8.1	User interface for plan generation block	106
5.8.1.1	Specification of operators	106
5.8.1.2	Specification of initial world and goal condition	107
5.8.1.3	Specification of domain rules	107
5.8.1.4	Specification of resource types	108
5.8.1.5	Inserting an action	108
5.8.2	The network maintenance block	108
5.8.3	Reasoner block	109
5.8.3.1	Inferential reasoning	110
5.8.3.2	Reasoning with resources	110
5.8.4	Planning process in CATRACT	111
5.9	Implementation of CATRACT	112
5.9.1	Network management functions	112
5.9.2	Reasoning functions	114
5.9.3	Interface functions	115
5.9.4	Planning using CATRACT	115
5.10	An application	116

CONTENTS	ix
5.10.1 The domain of investigation	117
5.10.2 Answering the queries	118
5.10.3 An Example	118
5.10.4 Query and propagation	119
5.11 Conclusion	121
6 Uncertainty in temporal representation and reasoning	123
6.1 Introduction	123
6.2 Qualitative and quantitative reasoning	124
6.3 Topology of imprecise time	126
6.3.1 Imprecise time instants	127
6.3.2 Imprecise time intervals	132
6.3.3 Imprecise time duration	133
6.3.4 Relationships between imprecise time instants	133
6.3.5 Relationship between imprecise time intervals	134
6.4 Integration of qualitative and quantitative TR	137
6.5 Conclusion	141
7 Conclusion	143
7.1 Summary of the thesis	143
7.2 Limitations of the approach	147
7.3 Future directions	147
8 Bibliography	149